

Tele-operated Robot for Backhoe (RoboQ)





The Tele-robot is easy to transport. Once at the disaster site, it can be attached to almost any commercially available backhoe.

Tele-operated robot for bulldozers (BuruQ)



Tele-operated robot for crawler dumps (KuroQ)



Tele-operation

FUJITA CORPORATION



\sim FUJITA's unmanned construction technology for removal of soil and rocks using ultra-remote operation \sim

This unmanned construction system enables us to remotely control construction vehicles used in the excavation, loading, transportation and disposal of soils and rocks from a remote operation room located in a safe area by using stereoscopic imaging, computer graphics and monitors. Using this system, equipment can be controlled at distances of up to 3 km. This system was adopted as an unmanned construction pilot project for the removal of soils and rocks at the Mizunashi area in Mt.Unzen-Fugen – as part of a "Field test program" for the Ministry of Construction (now the Ministry of Land, Infrastructure and Transportation).







Control room

<Characteristics>

- 1) Ultra-remote control can be performed from a distance of up to 3 km through use of communication relay cars.
- 2) Construction vehicles can be remotely controlled simultaneously using bidirectional communication systems.
- 3) Using monitors in the remote control room, realistic remote control is possible by using stereoscopic images, sounds and computer graphics.
- 4) Vehicle maintenance problems can be avoided through transmission of realtime data about their mechanical condition to the control room.
- 5) Excavation management (excavation volume, excavation accuracy, progress and positions of vehicles) can be performed using GPS and total station.





Application to demolition work



Application to installation of concrete blocks

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